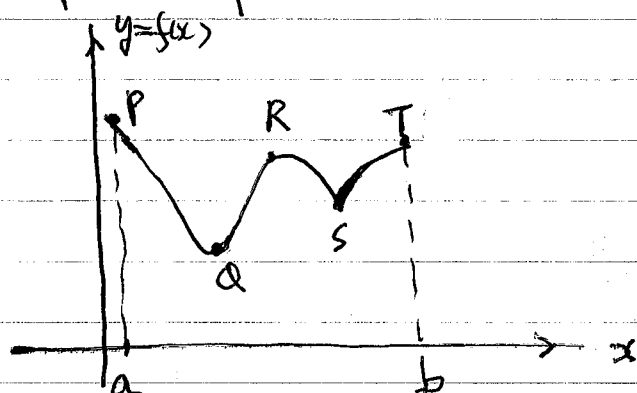


Optimization of functions of several variables.

Recall function of one variable case: $y = f(x)$, $a \leq x \leq b$.



P = Absolute/Global maximum (the highest pt.)

Q = Absolute/Global minimum ("lowest pt.")

S = local minimum

R, T = local maximum

Definition: For any point $c \in (a, b)$, it is said to be critical point of f iff either (i) $f'(c) = 0$ or (ii) $f'(c)$ does not exist.

Th^m (Fundamental theorem for optimization) Let f be a continuous function over (a, b) , we have

(i) If there is a local max or local min. at $c \in (a, b)$, then c is a critical point of f .

(ii) If f is continuous on $[a, b]$, then f attains an absolute maximum and an absolute minimum over $[a, b]$. Further, the abs. max. and abs. min. are being attained at either a critical point inside (a, b) or at the end pts.

Consider now the case of function of 2 variables:

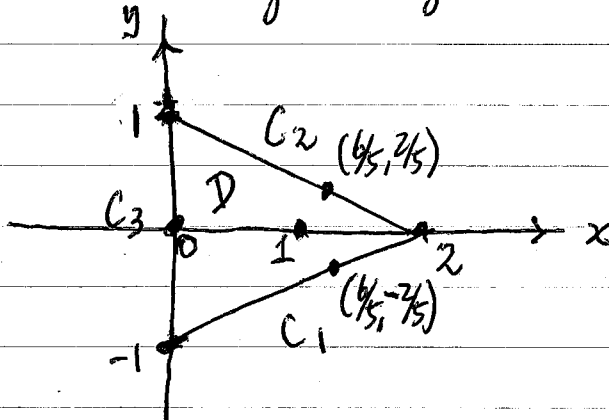
$$z = f(x, y), (x, y) \in D$$

D is the domain of f , an open connected set in the xy plane with boundary ∂D . Exactly the same theory could be carried over.

Defn. Given f continuous over D , $(a, b) \in D$ is said to be a critical point of f either (i) $\frac{\partial f}{\partial x}(a, b) = \frac{\partial f}{\partial y}(a, b) = 0$ or (ii) one of the $\frac{\partial f}{\partial x}(a, b)$, $\frac{\partial f}{\partial y}(a, b)$ fails to exist.

Theorem: Given $z = f(x, y)$ a continuous function over D , if f attains a local minimum or a local maximum at $(a, b) \in D$, then (a, b) is a critical point of f . Further, if D is bounded and f is continuous over $\bar{D} = D \cup \partial D$ (ie. f is continuous up to ∂D , the boundary of D), then f attains an absolute max. and an absolute min. over \bar{D} , which is either a critical point or a boundary point.

Ex. Find the absolute max and the absolute min. of $f(x, y) = x^2 + y^2 - 2x$, $(x, y) \in D$ where D is the triangular region as shown below.



Solution =

$f(x, y)$ is a polynomial in x & y , so it is continuous, further D is a bounded domain, therefore, the hypothesis of the theorem are satisfied.

Let us first figure out all the critical points in D by setting

$$\frac{\partial f}{\partial x} = 2x - 2 = 0 \quad \text{and} \quad \frac{\partial f}{\partial y} = 2y = 0 \Rightarrow (1, 0) \text{ is a critical pt.}$$

Since the abs. max. and abs. min. could also be attained at ∂D , we need to find out the max & min along C_1 , C_2 and C_3 .

$$\text{Along } C_1, \quad y = \frac{x}{2} - 1, \quad 0 \leq x \leq 2 \Rightarrow f(x, y) = x^2 + \left(\frac{x}{2} - 1\right)^2 - 2x = \frac{5}{4}x^2 - 3x + 1, \quad 0 \leq x \leq 2.$$

$$\text{Setting } f'(x) = \frac{5}{2}x - 3 = 0 \Rightarrow x = \frac{6}{5} \therefore \left(\frac{6}{5}, -\frac{2}{5}\right) \text{ is a critical pt. along } C_1.$$

$$\text{Along } C_2, \quad y = -\frac{x}{2} + 1, \quad 0 \leq x \leq 2 \Rightarrow \left(\frac{6}{5}, \frac{2}{5}\right) \text{ is a critical point along } C_2.$$

$$\text{Along } C_3, \quad x = 0, \quad f(x, y) = y^2, \quad -1 \leq y \leq 1 \Rightarrow (0, 0) \text{ is a critical pt. along } C_3.$$

Finally, we must also take into consideration the end points of C_1, C_2 & C_3 which amounts to the corner points $(0, \pm 1), (2, 0)$. Thus, there are all together 7 points where the abs. max & abs. min of f could be attained.

Evaluating f at those pts,

$$f(1,0) = -1, \quad f\left(\frac{1}{2}, \pm\frac{1}{2}\right) = -\frac{4}{5}, \quad f(0,0) = 0, \quad f(0, \pm 1) = 1 \quad \text{and} \quad f(2,0) = 0.$$

Therefore $f(1,0) = -1$ is the abs. min. and $f(0, \pm 1) = 1$ are abs. max. //

Ex. (D is unbounded) Find the abs. maximum of $z = f(x,y) = \frac{8x^3}{3} + 4y^3 - x^4 - y^4$

Solution:

First we observe that as $x, y \rightarrow \pm\infty$, $f(x,y) \rightarrow -\infty$ \therefore there is no absolute minimum. Further, for (x,y) in the 1st quadrant which is near $(0,0)$, $f(x,y)$ is positive, hence there must be an absolute max. which is positive. At the abs. max, we have

$$\begin{cases} \frac{\partial f}{\partial x} = 8x^2 - 4x^3 = 0 \Rightarrow x = 0, 2 \\ \frac{\partial f}{\partial y} = 12y^2 - 4y^3 = 0 \Rightarrow y = 0, 3 \end{cases}$$

(note that $\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}$ always exist and there is no critical points of the 2nd type).

Thus, $(0,0), (0,3), (2,0)$ and $(2,3)$ are the critical points where the abs. max of f would be attained. Evaluating $f(x,y)$ at these pts.

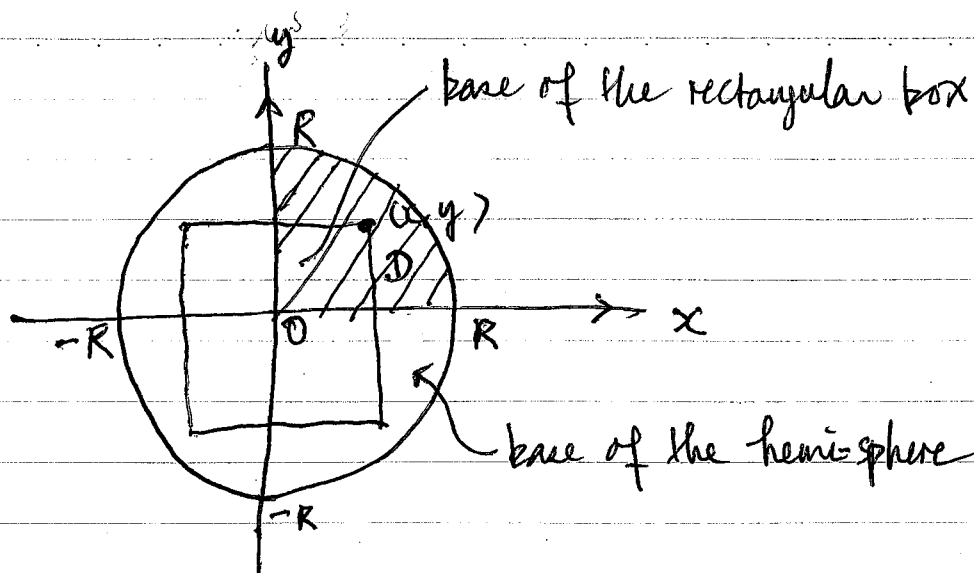
$$f(0,0) = 0, \quad f(2,0) = \frac{16}{3}, \quad f(0,3) = 27, \quad f(2,3) = \frac{97}{3}$$

Thus, $f(2,3) = \frac{97}{3}$ is our absolute maximum //

Ex. What is the largest volume of a rectangular box that could be inscribed in a hemisphere of radius R ? We assume one face of the box is on the base of the base of the hemisphere.

Solution

Without loss of generality, we may assume the center of the rectangular base of the box is at the origin of the $x-y$ plane (see figure). Further, we let (x,y) be the corner of the base in the 1st quadrant.



We note that the equation of the hemispherical surface is $z = \sqrt{R^2 - x^2 - y^2}$, which is also the height of the rectangular box, the volume of the box is therefore,

$$f(x, y) = 4xy \sqrt{R^2 - x^2 - y^2}, \quad (x, y) \in D$$

where D is the quarter circular region of radius R in the 1st quadrant. Since f is continuous over D , f must attain its absolute max and its absolute minimum over D . Further $f(x, y) = 0$ along ∂D , the abs. max. must be attained at the interior of D where $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$ both exist. Thus, at the point (x, y) where the absolute maximum of f is attained, we have

$$\frac{\partial f}{\partial x} = 4y \sqrt{R^2 - x^2 - y^2} - \frac{4x^2}{\sqrt{R^2 - x^2 - y^2}} = \frac{4y(R^2 - y^2 - 2x^2)}{\sqrt{R^2 - x^2 - y^2}} = 0$$

$$\Rightarrow y^2 + 2x^2 = R^2 \quad \text{--- (1)} \quad (y=0 \text{ could be rejected as mentioned before})$$

Similarly, we also have $\frac{\partial f}{\partial y} = 0$ implying

$$x^2 + 2y^2 = R^2 \quad \text{--- (2)}$$

Solving (1) and (2) simultaneously, we have $x = y = \frac{R}{\sqrt{3}}$ which must be the point where the abs. max. of $f(x, y)$ is being attained (note that such result could actually be expected by symmetry argument).

The corresponding max. capacity of the box is therefore,

$$f\left(\frac{R}{\sqrt{3}}, \frac{R}{\sqrt{3}}\right) = 4\left(\frac{R}{\sqrt{3}}\right)^2 \sqrt{R^2 - \frac{2}{3}R^2} = \frac{4R^2}{3} \frac{R}{\sqrt{3}} = \frac{4R^3}{3\sqrt{3}} \quad // \cdot \frac{1}{\sqrt{3}}$$

2nd derivative test for local max. and local min. when we have a smooth critical point

Th^o (2nd Derivative Test) Given $z = f(x, y)$, $(x, y) \in D$ and let $(a, b) \in D$ be a smooth critical point (twice continuously differentiable) where $\frac{\partial f}{\partial x}(a, b) = \frac{\partial f}{\partial y}(a, b) = 0$.

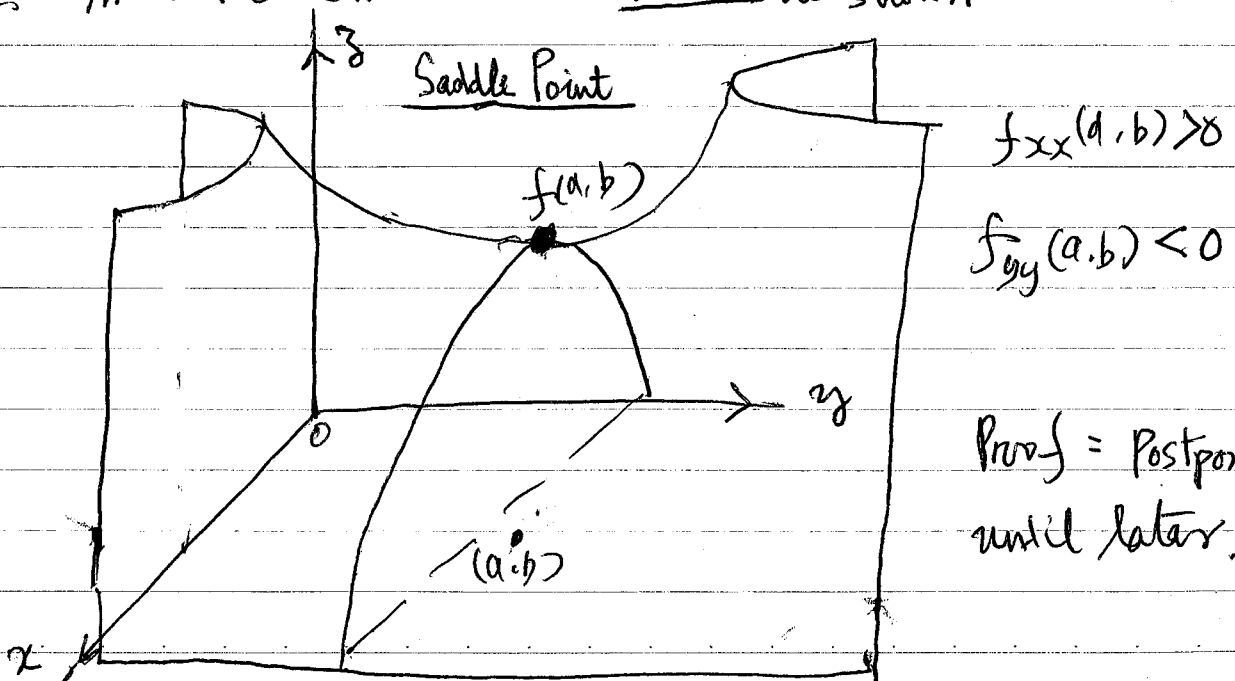
We define the discriminant $D_f(a, b)$ by

$$D_f(a, b) = f_{xx}(a, b)f_{yy}(a, b) - (f_{xy}(a, b))^2,$$

then we have

- (i) If $D(a, b) > 0$ and $f_{xx}(a, b) > 0$, f is a local min. at (a, b)
- (ii) If $D(a, b) > 0$ and $f_{xx}(a, b) < 0$, f is a local max at (a, b)
- (iii) If $D(a, b) < 0$, f has a saddle point at (a, b) (see figure below)
- (iv) If $D(a, b) = 0$, the test is inconclusive.

Remark: In case $D(a, b) > 0$, $f_{xx}(a, b)$ and $f_{yy}(a, b)$ share the same sign. In case $D(a, b) < 0$, $f_{xx}(a, b)$ and $f_{yy}(a, b)$ are opposite in sign. In that case we have a saddle as shown



Ex. Back to the earlier example $f(x,y) = \frac{8x^3}{3} + 4y^3 - x^4 - y^4$.

$$\frac{\partial f(x,y)}{\partial x} = 8x^2 - 4x^3 = 0, \quad \frac{\partial f(x,y)}{\partial y} = 12y^2 - 4y^3 = 0$$

at $(0,0)$, $(2,0)$, $(0,3)$ and $(2,3)$

$$D_f = f_{xx}f_{yy} - (f_{xy})^2 \\ = (16x - 12x^2)(4y - 12y^2) - (0)^2$$

$$D_f(0,0) = D_f(2,0) = D_f(0,3) = 0, \text{ test fails.}$$

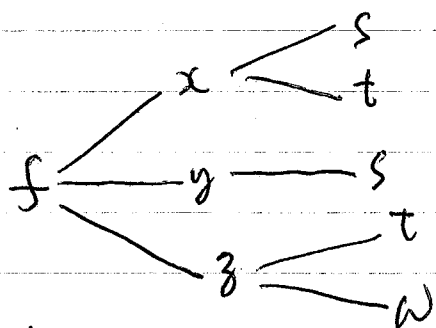
$$\text{But at } (2,3), f_{xx}(2,3) < 0, f_{yy} < 0, D_f(2,3) > 0$$

\therefore we have local max at $(2,3)$ (which turns out to be an abs. max. as well).

Chain Rule for Partial Differentiation

Since we are dealing with functions of multi-variable, there is no single chain rule that could handle every possible case, but each individual case could be handled using a tree diagram.

Ex. Given $f(x,y,z)$ where x is a function of s & t , y a fct of s and z a function of t & w . As a result f is a function of s, t and w . The relationship could be expressed through a tree diagram.



we have $\frac{\partial f}{\partial s} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial s} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial s}$, $\frac{\partial f}{\partial t} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial t} + \frac{\partial f}{\partial z} \frac{\partial z}{\partial t}$

$$\frac{\partial f}{\partial w} = \frac{\partial f}{\partial z} \frac{\partial z}{\partial w}$$

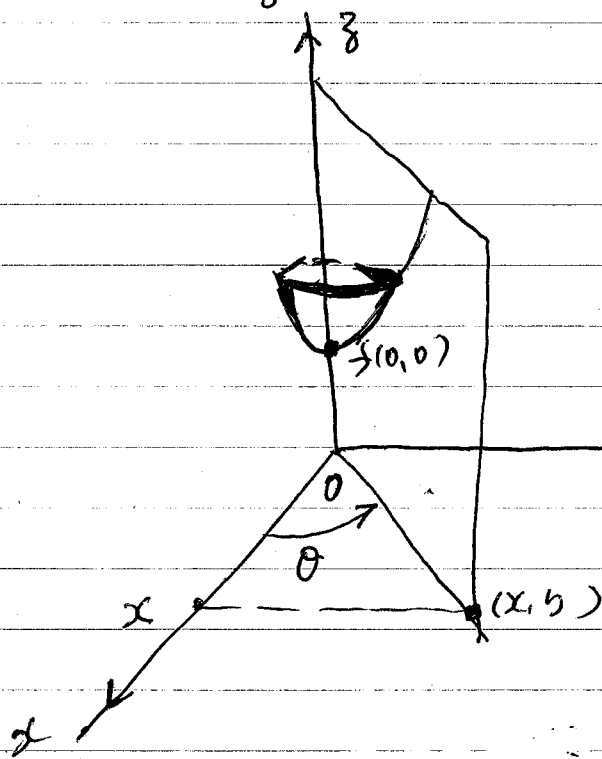
Ex. $f(x,y,z) = xyz$
 where $x = s^2 + t^2$, $y = st$, $z = tw^2$

Ex. Proof of the 2nd derivative test

Let $f(x, y)$ have a critical pt. at (a, b) where f is twice continuously differentiable

$$\text{and } \frac{\partial f}{\partial x}(a, b) = \frac{\partial f}{\partial y}(a, b) = 0$$

Without loss of generality, we assume (a, b) is at $(0, 0)$.
 In order to show that f either attains a local max or a local min at (a, b) , it boils down to showing that the curve of intersection between the surface $z = f(x, y)$ and ~~any~~ θ -plane (the vertical plane which makes an angle θ with the positive x -axis)



In this case, x and y are related through the eqn.

$$y = \tan \theta x$$

\Rightarrow equation of curve of intersection is given by

$$z = f(x, y) = f(x, \tan \theta x)$$

Thus, f has the tree diagram

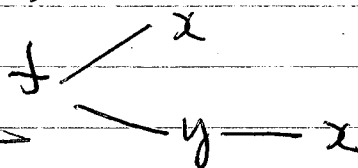


Diagram showing a local minimum at $(0, 0)$

Indeed, set $g(x) = f(x, x \tan \theta)$, \leftarrow equation of curve of intersection between the surface & the θ -plane

$$g'(x) = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \frac{dy}{dx} = f_x + f_y \tan \theta$$

Since $(0, 0)$ is a critical point, i.e. $\frac{\partial f}{\partial x}(0, 0) = \frac{\partial f}{\partial y}(0, 0)$, we must have

$$g'(0) = f_x(0, 0) + f_y(0, 0) \tan \theta = 0.$$

$$\text{Consider now } g''(\alpha) = f_{xx}(x, \tan \alpha x) + 2 \tan \alpha f_{xy}(x, \tan \alpha x) + f_{yy}(x, \tan \alpha x) \tan^2 \alpha$$

Here let us rule out the case $\theta = \frac{\pi}{2} + 3\frac{\pi}{2}$ (which actually corresponds to the case $x=0$), so that $\tan \theta$ exists.

$$g''(0) = f_{xx}(0,0) + 2f_{xy}(0,0) \tan \theta + f_{yy}(0,0) \tan^2 \theta$$

This is a quadratic function in $\tan \theta$ with discriminant

$$\begin{aligned} \Delta &= 4f_{xy}(0,0)^2 - 4f_{xx}(0,0)f_{yy}(0,0) \\ &= -4D_f(0,0) \end{aligned}$$

Now that if $D_f(0,0) > 0$, $\Delta < 0 \Rightarrow g''(0) < 0$ or $g''(0) > 0$ for every $\theta \neq \frac{\pi}{2}$ and $3\frac{\pi}{2}$ and the sign of $g''(0)$ is determined by

$$g''(0) > 0 \text{ if } f_{yy}(0,0) > 0 \text{ (alternatively } f_{xx}(0,0) > 0)$$

$$g''(0) < 0 \text{ if } f_{yy}(0,0) < 0 \text{ (alternatively } f_{xx}(0,0) < 0)$$

Thus, $D_f(0,0) > 0$ and $f_{xx}(0,0) > 0 \Rightarrow$ a local minimum at $(0,0)$ in all θ -direction such that $\theta \neq \frac{\pi}{2}, 3\frac{\pi}{2}$

$$D_f(0,0) > 0 \text{ and } f_{xx}(0,0) < 0 \Rightarrow \text{a local maximum}$$

at $(0,0)$ in all θ direction s.t. $\theta \neq \frac{\pi}{2}, 3\frac{\pi}{2}$

Finally, we consider the case when $\theta = \frac{\pi}{2}$ or $3\frac{\pi}{2}$, but this is the trivial case when $x=0$ (i.e. the θ -plane coincides with the y - z plane), we'll leave it as an exercise for the readers.

In the case when $D_f(0,0) < 0$, we have $g''(0) > 0$ along certain θ -directions & $g''(0) < 0$ along some other θ directions, this would correspond to the saddle point case //

Implicit Function Theorem

Th^m. Consider the equation $F(x, y, z) = 0$ such that: F is continuously differentiable in all its arguments. Suppose further that at some point (x_0, y_0, z_0) , $\frac{\partial F}{\partial z}(x_0, y_0, z_0) \neq 0$, then $F(x, y, z) = 0$ defines implicitly z as a function of x & y locally at (x_0, y_0) , i.e. we could find a small neighborhood of (x_0, y_0) such that $z = h(x, y)$ satisfies

$$F(x, y, h(x, y)) = 0$$

Further, $z = h(x, y)$ is partially differentiable with respect to x & with respect to y , with

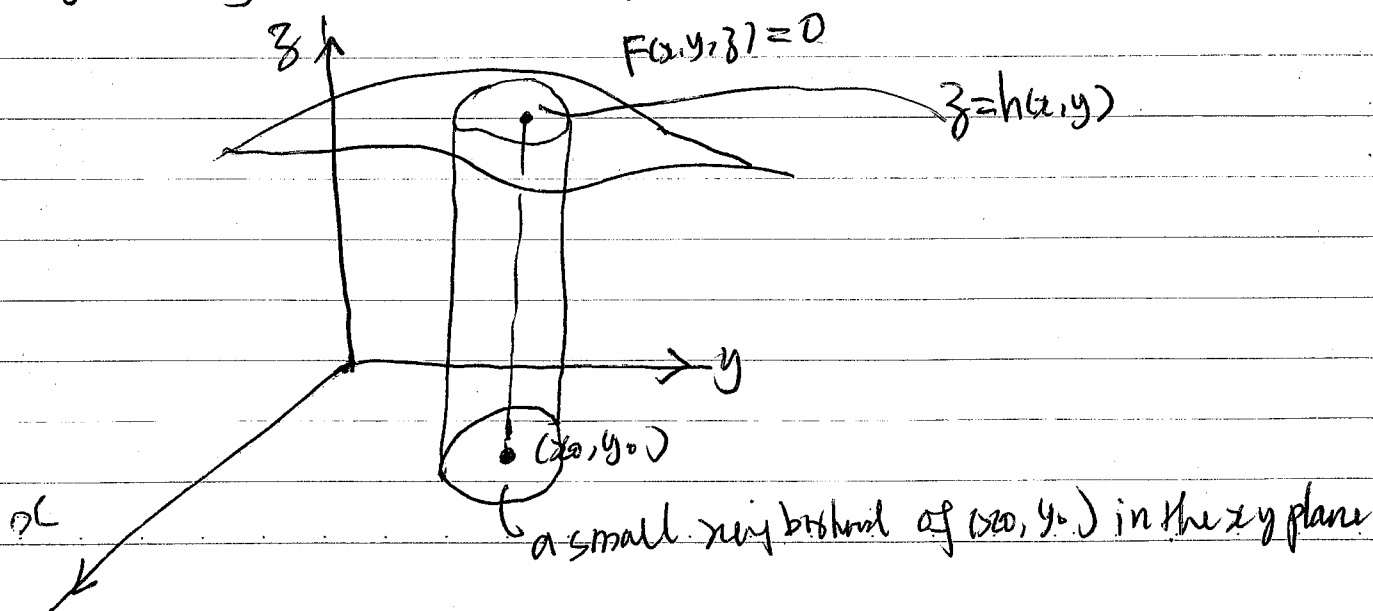
$$\frac{\partial z}{\partial x}(x_0, y_0) = \frac{\partial h}{\partial x}(x_0, y_0) = - \frac{\frac{\partial F}{\partial x}(x_0, y_0, z_0)}{\frac{\partial F}{\partial z}(x_0, y_0, z_0)}$$

and

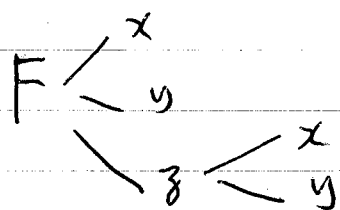
$$\frac{\partial z}{\partial y}(x_0, y_0) = \frac{\partial h}{\partial y}(x_0, y_0) = - \frac{\frac{\partial F}{\partial y}(x_0, y_0, z_0)}{\frac{\partial F}{\partial z}(x_0, y_0, z_0)}$$

Idea of the Theorem:

Suppose indeed, $F(x, y, z) = 0$ defines z implicitly as function of x & y locally at (x_0, y_0) (see picture below)



Nearby (x_0, y_0) , we have $F(x, y, h(x, y)) \equiv 0$, we could look upon L.H.S. as a function of $x + y$. Thus,



Differentiate both sides partially with respect to x & y respectively,

$$\frac{\partial F(x, y, z)}{\partial x} + \frac{\partial F(x, y, z)}{\partial z} \frac{\partial h(x, y)}{\partial x} = 0$$

$$\text{In particular, at } (x_0, y_0, z_0), \frac{\partial F(x, y)}{\partial x} = \frac{-\frac{\partial F(x_0, y_0, z_0)}{\partial x}}{\frac{\partial F(x_0, y_0, z_0)}{\partial z}}$$

$$\therefore \frac{\partial z}{\partial x} = -\frac{\frac{\partial F}{\partial x}}{\frac{\partial F}{\partial z}} \text{ at } (x_0, y_0)$$

$$\frac{\partial z}{\partial y} = -\frac{\frac{\partial F}{\partial y}}{\frac{\partial F}{\partial z}} \text{ is proved analogously.}$$

Remarks

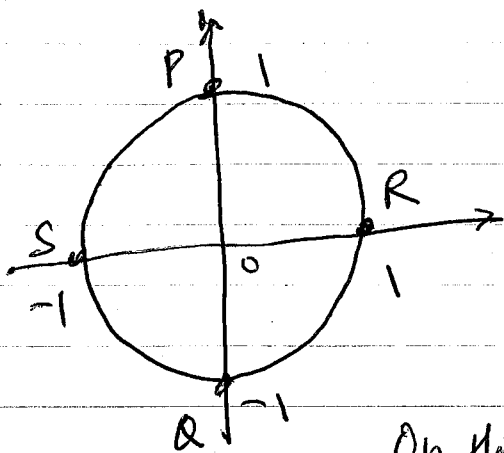
This result is not just confined to the case $F(x, y, z) \equiv 0$, it applies to F which is a function of n variables for any $n \geq 2$

$$\text{Ex. } F(x_1, x_2, \dots, x_n) = 0$$

$$\frac{\partial F}{\partial x_n} \neq 0 \Rightarrow \frac{\partial x_n}{\partial x_i} = -\frac{F_{x_i}}{F_{x_n}} \quad \forall i=1, \dots, n-1$$

and so on.

Ex Consider $F(x,y) = x^2 + y^2 - 1 = 0$, $\frac{\partial F}{\partial x} = 2x$, $\frac{\partial F}{\partial y} = 2y$



at $P(0,1)$ & $Q(0,-1)$, $\frac{\partial F}{\partial x} = 0$ but $\frac{\partial F}{\partial y} \neq 0$

\therefore nearby P & Q , we could solve for y as a fct of x . Indeed, we have

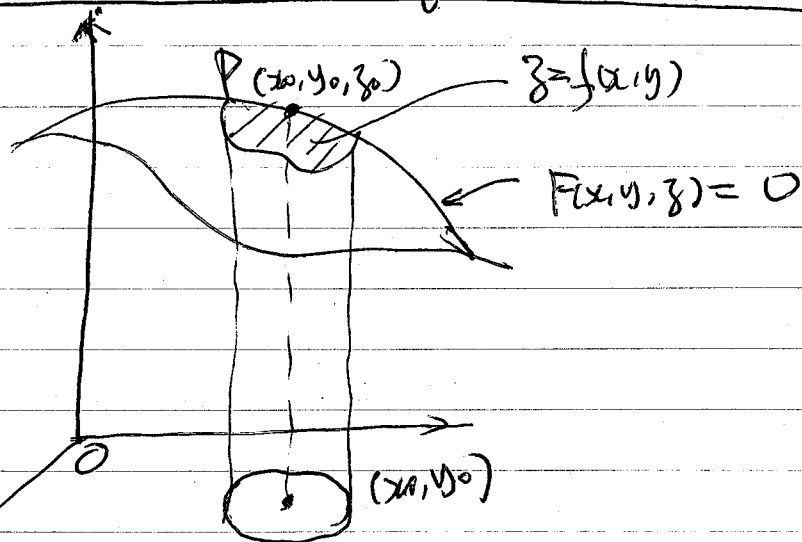
$$y = \sqrt{1-x^2} \text{ nearby } P \text{ & } y = -\sqrt{1-x^2} \text{ at } Q$$

On the other hand, at $S(-1,0)$ & $R(1,0)$

$$\frac{\partial F}{\partial x} \neq 0$$

We could therefore solve for x as a fct of y nearby R & S .
i.e. we have $x = \sqrt{1-y^2}$ nearby R & $x = -\sqrt{1-y^2}$ nearby S .

Tangent Plane to the surface $F(x,y,z) = 0$



Suppose one of the $\frac{\partial F}{\partial x}(P)$, $\frac{\partial F}{\partial y}(P)$ & $\frac{\partial F}{\partial z}(P) \neq 0$, without loss of generality, assume $\frac{\partial F}{\partial z}(x_0, y_0, z_0) \neq 0$

Then locally at P , we could have $z = f(x,y)$ s.t.

$$\frac{\partial f}{\partial x}(x_0, y_0) = - \frac{\frac{\partial F}{\partial x}(P)}{\frac{\partial F}{\partial z}(P)}, \quad \frac{\partial f}{\partial y} = - \frac{\frac{\partial F}{\partial y}(P)}{\frac{\partial F}{\partial z}(P)}$$

The normal vector N at P is given by

$$\vec{N} = \left\langle -\frac{\partial f}{\partial x}(x_0, y_0), -\frac{\partial f}{\partial y}(x_0, y_0), 1 \right\rangle$$

$$= \left\langle \frac{\frac{\partial F}{\partial x}(P)}{\frac{\partial F}{\partial z}(P)}, \frac{\frac{\partial F}{\partial y}(P)}{\frac{\partial F}{\partial z}(P)}, 1 \right\rangle$$

or we could simply take $\vec{N} = \left\langle \frac{\partial F}{\partial x}(P), \frac{\partial F}{\partial y}(P), \frac{\partial F}{\partial z}(P) \right\rangle$

We denote it as $\nabla F(P)$.

The other two possibilities of having $\frac{\partial F}{\partial x}(P) \neq 0$ or $\frac{\partial F}{\partial y}(P) \neq 0$

could be argued in exactly the same way.

Ex. Consider the surface $F(x, y, z) = 2z^3 + (x+y)z^2 + x^2 + y^2 = 14$,
 $P(2, 2, 1)$ is a point on the surface. We could take

$\vec{N} = \nabla F(2, 2, 1)$ as a normal vector at the pt. $(2, 2, 1)$ (note that whether we bring the 14 to the RHS or not is irrelevant).

$$\nabla F = \left\langle \frac{\partial F}{\partial x}, \frac{\partial F}{\partial y}, \frac{\partial F}{\partial z} \right\rangle = \left\langle z^2 + 2x, z^2 + 2y, 6z^2 + 2(x+y)z \right\rangle$$

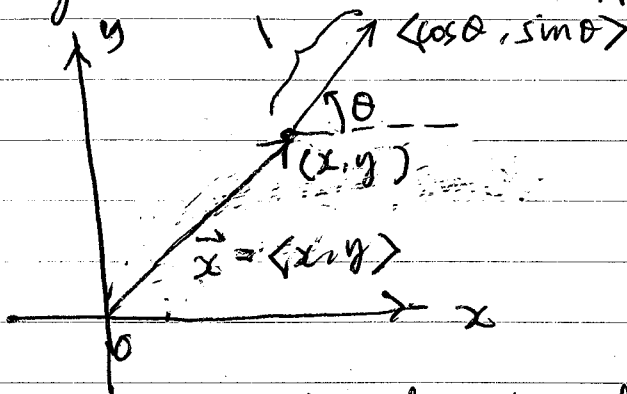
$$\Rightarrow \vec{N} = \nabla F(2, 2, 1) = \langle 5, 5, 14 \rangle$$

Equation of tangent plane is therefore,

$$5(x-2) + 5(y-2) + 14(z-1) = 0 //$$

Directional Derivatives of $f(x,y)$

This is a generalization of $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$ for a function $f(x,y)$. Let now $\vec{u} = \langle \cos\theta, \sin\theta \rangle$ be a direction vector in the xy plane (recall, a direction vector \vec{u} is a vector pointing in a certain direction of length 1).



We define the directional derivative of f in the direction \vec{u} as follows. We use vector notation with $\vec{x} = \langle x, y \rangle$ and $\vec{x} + h\vec{u} = \langle x + h\cos\theta, y + h\sin\theta \rangle$ and define

$$\begin{aligned} \frac{\partial f}{\partial \vec{u}}(\vec{x}) &= \lim_{h \rightarrow 0} \frac{f(\vec{x} + h\vec{u}) - f(\vec{x})}{h} \\ &= \lim_{h \rightarrow 0} \frac{f(x + h\cos\theta, y + h\sin\theta) - f(x, y)}{h} \end{aligned}$$

We construct the auxiliary

$$g(t) = f(x + t\cos\theta, y + t\sin\theta)$$

$$\text{then } g'(t) = \frac{\partial f}{\partial x}(x + t\cos\theta, y + t\sin\theta)\cos\theta + \frac{\partial f}{\partial y}(x + t\cos\theta, y + t\sin\theta)\sin\theta$$

$$\text{In particular, } g'(0) = \frac{\partial f}{\partial x}(x, y)\cos\theta + \frac{\partial f}{\partial y}(x, y)\sin\theta$$

$$\text{But } g'(0) = \lim_{h \rightarrow 0} \frac{g(h) - g(0)}{h} \text{ also,}$$

$$\text{thus } \lim_{h \rightarrow 0} \frac{f(x + h\cos\theta, y + h\sin\theta) - f(x, y)}{h} = \frac{\partial f}{\partial x}\cos\theta + \frac{\partial f}{\partial y}\sin\theta$$

Remark: Note that $\frac{\partial f}{\partial \vec{i}}(x, y) = \frac{\partial f}{\partial x}(x, y)$, $\frac{\partial f}{\partial \vec{j}}(x, y) = \frac{\partial f}{\partial y}(x, y)$

In general, suppose we have a function of n variables $f(x_1, \dots, x_n)$, let $\vec{x} = \langle x_1, \dots, x_n \rangle$ and let $\vec{u} = \langle u_1, \dots, u_n \rangle$, $|\vec{u}|=1$ be any direction vector, we define

$$\frac{\partial f(\vec{x})}{\partial u} = \lim_{h \rightarrow 0} \frac{f(\vec{x} + h\vec{u}) - f(\vec{x})}{h}$$

to be the directional derivative of $f(\vec{x})$ in the direction \vec{u} .

Definition: Given $f(\vec{x}) = f(x_1, \dots, x_n)$, $\vec{x} = (x_1, \dots, x_n)$, we define the gradient vector of f by

$$\nabla f(\vec{x}) = \left\langle \frac{\partial f(x_1, \dots, x_n)}{\partial x_1}, \frac{\partial f(x_1, \dots, x_n)}{\partial x_2}, \dots, \frac{\partial f(x_1, \dots, x_n)}{\partial x_n} \right\rangle$$

Then along any direction \vec{u} , we have

$$\frac{\partial f(\vec{x})}{\partial u} = \nabla f(\vec{x}) \cdot \vec{u} = \frac{\partial f(x_1, \dots, x_n)}{\partial x_1} u_1 + \dots + \frac{\partial f(x_1, \dots, x_n)}{\partial x_n} u_n$$

Remark: $\frac{\partial f}{\partial u}$ is the rate of change of f in the direction of \vec{u} .

Ex. Given $f(x, y, z) = x^2 + y^2 + z^2 - 2xy + 2xz + yz$, find the directional derivative of f at the point $P(1, 0, 2)$ in the direction from P to $Q(2, 3, 3)$

Solution:

$$\nabla f(x, y, z) = \langle 2x - 2y + 2z, 2y - 2x + z, 2z + 2x + y \rangle$$

$$\therefore \nabla f(1, 0, 2) = \langle 2 + 4, -2 + 2, 4 + 2 \rangle = \langle 6, 0, 6 \rangle$$

and the direction vector in the direction of $\vec{PQ} = \langle 1, 3, 1 \rangle$ is given

$$\text{by } \vec{u} = \frac{\langle 1, 3, 1 \rangle}{\sqrt{1+9+1}} = \left\langle \frac{1}{\sqrt{11}}, \frac{3}{\sqrt{11}}, \frac{1}{\sqrt{11}} \right\rangle$$

$$\therefore \frac{\partial f}{\partial u}(1, 0, 2) = \nabla f(1, 0, 2) \cdot \vec{u} = \langle 6, 0, 6 \rangle \cdot \left\langle \frac{1}{\sqrt{11}}, \frac{3}{\sqrt{11}}, \frac{1}{\sqrt{11}} \right\rangle = \frac{12}{\sqrt{11}}$$

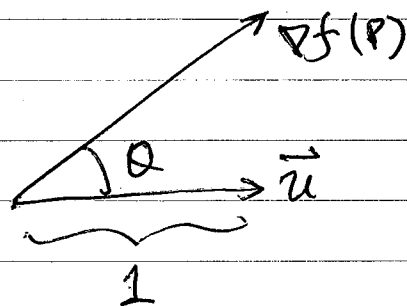
Direction in which f changes most rapidly and the Direction in which the rate of change of f is a minimum.

Let $P(x_0, y_0, z_0)$ be any point belonging to the domain of f and let \vec{u} be any direction, then

$$\frac{\partial f}{\partial \vec{u}}(P) = \nabla f(P) \cdot \vec{u}$$

By dot product's property, $\frac{\partial f}{\partial \vec{u}}(P) = |\nabla f(P)| |\vec{u}| \cos \theta = |\nabla f(P)| \cos \theta$

where θ is the \angle between $\nabla f(P)$ and \vec{u}



We observe that, $\frac{\partial f}{\partial \vec{u}}(P)$ attains its maximum value of $|\nabla f(P)|$ when $\theta = 0$, i.e. when \vec{u} is in the same direction of $\nabla f(P)$.

Similarly, the rate of change of f i.e. $\frac{\partial f}{\partial \vec{u}}(P)$ attains its minimum value of $-|\nabla f(P)|$ when \vec{u} is in the opposite direction of $\nabla f(P)$.

Ex. Suppose the temperature T (in $^{\circ}\text{C}$) at the pt. (x, y, z) in space is given by $T(x, y, z) = x^3 - xy^2 - z$, in which direction does the temperature increase most rapidly at $P(1, 1, 0)$? What is the maximal rate of change at $P(1, 1, 0)$?

Solution = $\nabla T(x, y, z) = \langle 3x^2 - y^2, -2xy, -1 \rangle$

at $P(1, 1, 0)$, maximum rate of change of T is in the direction of $\nabla T(1, 1, 0) = \langle 2, -2, -1 \rangle$ or $\vec{u} = \langle \frac{2}{3}, \frac{-2}{3}, \frac{-1}{3} \rangle$ with max rate of change = $|\nabla T(1, 1, 0)| = 3$.